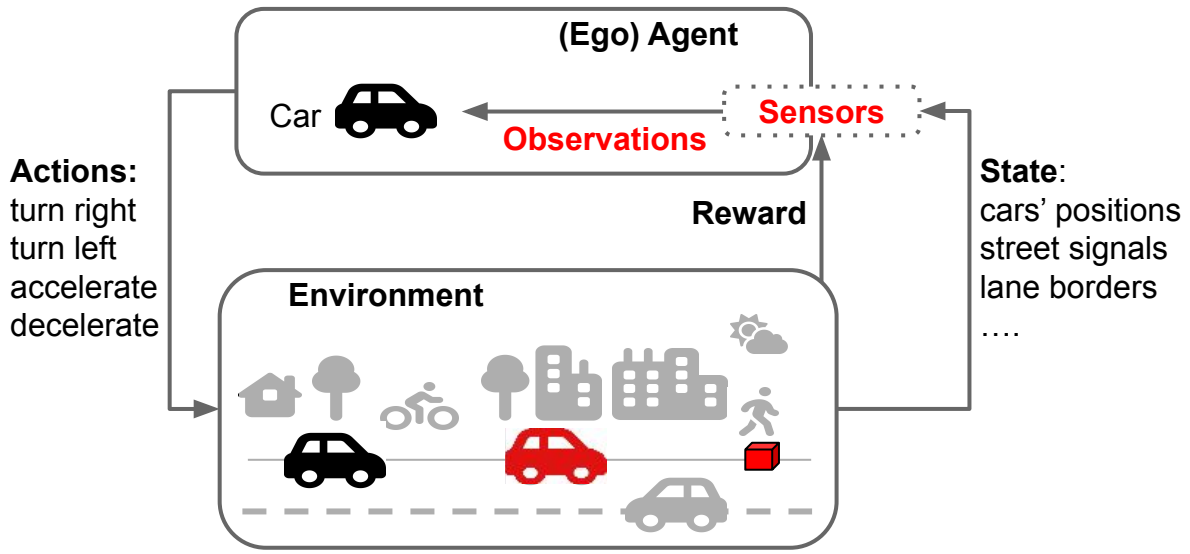

(Ego) Agent
Car
Sensors
Observations
Actions:
turn right
turn left
accelerate
decelerate
Reward
State:
cars' positions
street signals
lane borders
….
Environment