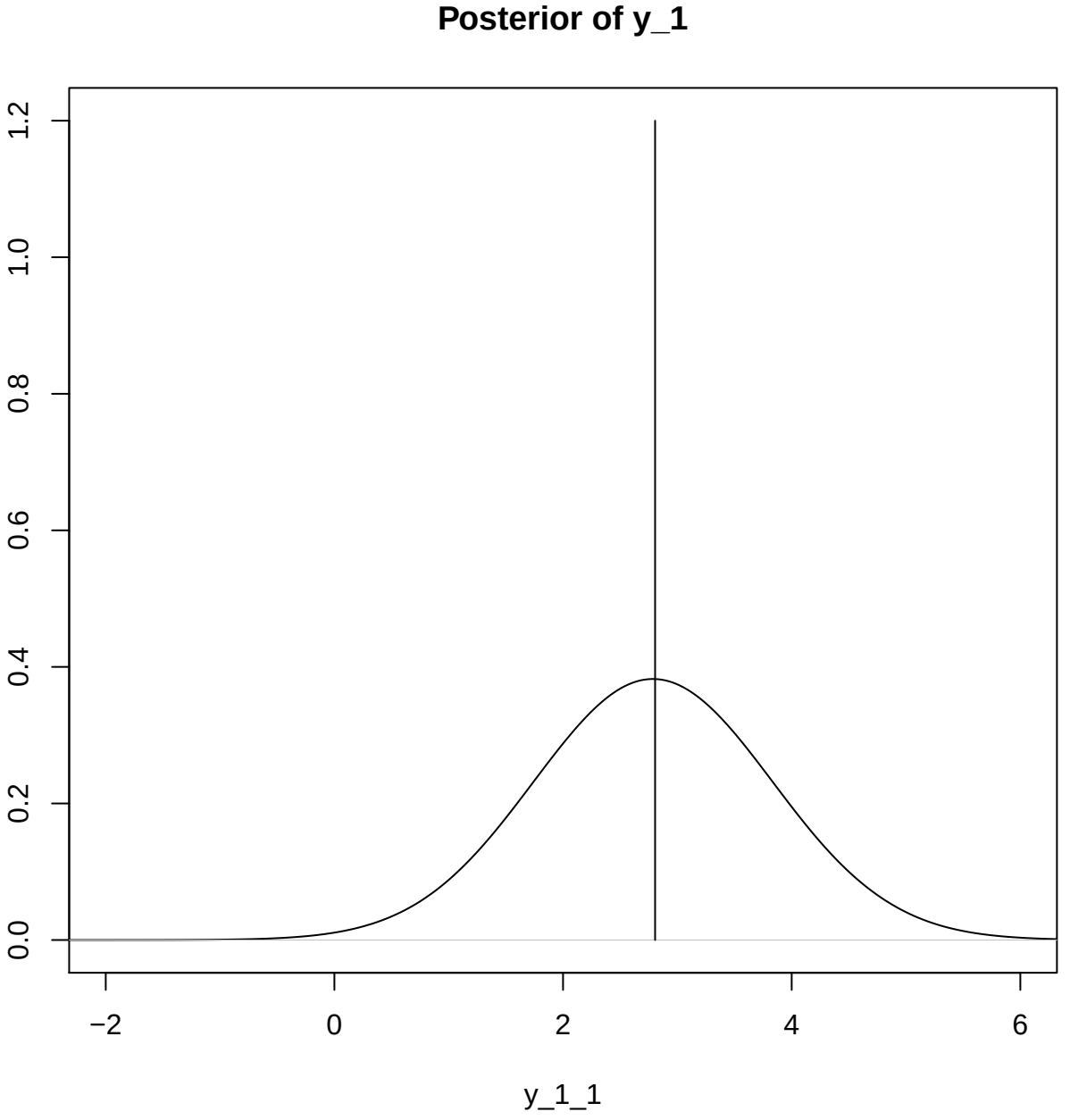

Posterior of y_1
1.2
1.0
0.8
0.6
0.4
0.2
0.0
−2
0
2
4
6
y_1_1