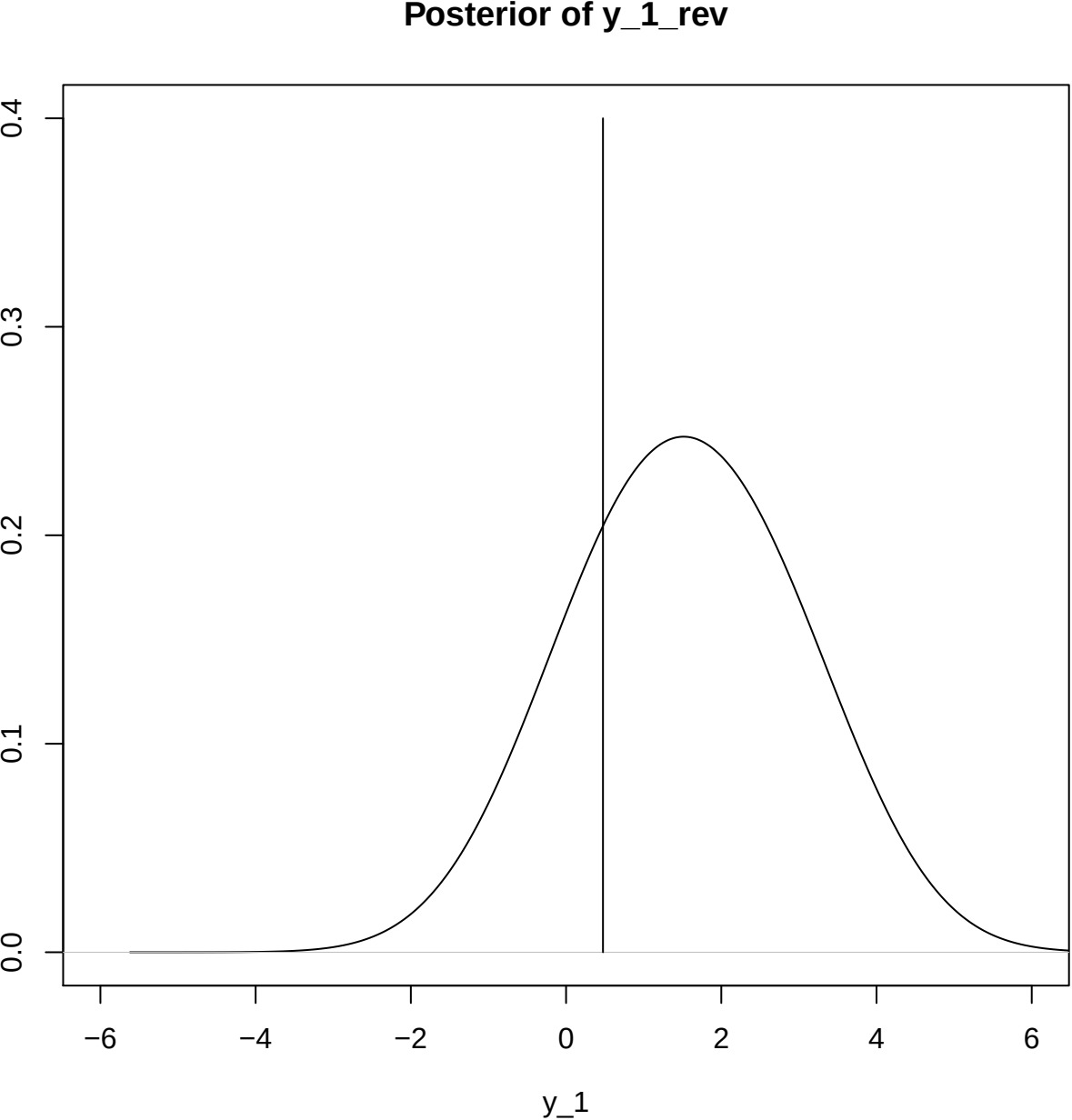

Posterior of y_1_rev
0.0
0.1
0.2
0.3
0.4
−6
−4
−2
0
2
4
6
y_1